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1	IS&R	L1	44758	("000358\$").PN. or ((382/124) or (359/196,220,221,209, 709,834)).CCLS. or ("356").CLAS.	USPAT	2004/10/1 3 16:11	
2	BRS	L2	14265	1 and scan\$5	USPAT	2004/10/1 3 16:08	
3	BRS	L3	12915	2 and optic\$5	USPAT	2004/10/1 3 16:09	
4	BRS	L4	11515	3 and detect\$5	USPAT	2004/10/1 3 16:09	
5	BRS	L5	449	4 and (fingerprint\$4 or biometric\$5)	USPAT	2004/10/1 3 16:10	
6	BRS	L6	186	5 and prism\$4	USPAT	2004/10/1 3 16:18	
7	BRS	L7	181	6 and light\$5	USPAT	2004/10/1 3 16:11	
8	BRS	L8	108	7 and rotat\$5	USPAT	2004/10/1 3 16:11	
9	BRS	L9	25	8 and symmetric\$5	USPAT	2004/10/1 3 16:12	
10	BRS	L10	97	8 and imag\$4	USPAT	2004/10/1 3 16:12	
11	BRS	L11	44	10 and motor\$4	USPAT	2004/10/1 3 16:13	
12	BRS	L12	4	11 and belt\$4	USPAT	2004/10/1 3 16:15	
13	BRS	L13	0	12 and dov\$4	USPAT	2004/10/1 3 16:17	
14	BRS	L14	92	10 and surfac\$4	USPAT	2004/10/1 3 16:14	
15	BRS	L15	89	14 and reflect\$5	USPAT	2004/10/1 3 16:15	
16	BRS	L16	88	15 and direct\$5	USPAT	2004/10/1 3 16:15	
17	BRS	L17	4	16 and belt\$4	USPAT	2004/10/1 3 16:16	
18	BRS	L18	0	16 and pechan	USPAT	2004/10/1 3 16:17	
19	BRS	L19	15750	arcuate near4 path	USPAT	2004/10/1 3 16:16	
20	BRS	L20	123	1 and 19	USPAT	2004/10/1 3 16:16	
21	BRS	L21	1	20 and pechan	USPAT	2004/10/1 3 16:17	
22	BRS	L22	0	13 and 19	USPAT	2004/10/1 3 16:17	
23	BRS	L23	78	3 and 19	USPAT	2004/10/1 3 16:18	

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1	BRS	L1	33394	scan\$4 near4 optical	USPAT	2004/10/08 12:54	
2	BRS	L2	4063	1 and prism	USPAT	2004/10/08 16:23	
3	BRS	L3	3885	2 and light\$	USPAT	2004/10/08 12:55	
4	BRS	L4	3086	3 and rotat\$4	USPAT	2004/10/08 12:56	
5	BRS	L5	1	4 and ((non-planar or non adj planar) near4 (prism))	USPAT	2004/10/08 16:05	
6	BRS	L6	1	5 and scanner	USPAT	2004/10/08 13:01	
7	BRS	L7	1	6 and detector	USPAT	2004/10/08 13:01	
8	BRS	L9	1	7 and imag\$4	USPAT	2004/10/08 13:02	
9	BRS	L10	1	9 and direct\$4	USPAT	2004/10/08 13:02	
10	BRS	L11	1	10 and reflect\$5	USPAT	2004/10/08 13:03	
11	BRS	L12	1	11 and fingerprint\$4	USPAT	2004/10/08 13:05	
12	BRS	L13	1	12 and surface	USPAT	2004/10/08 13:05	
13	BRS	L14	1	13 and internal\$5	USPAT	2004/10/08 13:05	
14	BRS	L15	1	14 and symmetr\$5	USPAT	2004/10/08 13:06	
15	BRS	L16	1	15 and axis	USPAT	2004/10/08 13:07	
16	BRS	L17	1	16 and motor	USPAT	2004/10/08 13:40	
17	BRS	L20	150	4 and (dove near3 prism)	USPAT	2004/10/08 14:45	
18	BRS	L21	0	20 and (pachan near3 prism)	USPAT	2004/10/08 14:44	
19	BRS	L22	16	20 and belt	USPAT	2004/10/08 16:06	
20	BRS	L24	4	22 and pulley	USPAT	2004/10/08 16:06	
21	BRS	L26	1	25 and electromagnetic\$4	USPAT	2004/10/08 13:41	
22	BRS	L25	4	24 and motor	USPAT	2004/10/08 13:42	
23	BRS	L27	0	20 and (arcuate near4 patch)	USPAT	2004/10/08 15:56	
24	BRS	L28	58	(arcuate near4 patch)	USPAT	2004/10/08 14:42	

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25	BRS	L29	0	28 and (pachan near3 prism)	USPA T	2004/10/08 15:54	
26	BRS	L30	0	1 and 28	USPA T	2004/10/08 14:43	
27	BRS	L31	1	pachan near3 prism	USPA T	2004/10/08 14:45	
28	BRS	L32	1	31 and rotat\$5	USPA T	2004/10/08 15:56	
29	BRS	L33	0	32 and (dove near3 prism)	USPA T	2004/10/08 16:05	
30	BRS	L34	0	32 and (dove)	USPA T	2004/10/08 14:46	
31	BRS	L35	0	(pachan near4 prism) and (arcuate near4 patch)	USPA T	2004/10/08 15:54	
32	BRS	L36	0	4 and (pachan near3 prism)	USPA T	2004/10/08 15:55	
33	BRS	L37	1	1 and (pachan near3 prism)	USPA T	2004/10/08 16:05	
34	BRS	L38	0	1 and (arcuate near4 patch)	USPA T	2004/10/08 16:04	
35	BRS	L39	6	scan\$5 and (arcuate near4 patch)	USPA T	2004/10/08 16:18	
36	BRS	L40	1	39 and optical	USPA T	2004/10/08 16:08	
37	BRS	L41	1	40 and rotat\$5	USPA T	2004/10/08 16:11	
38	BRS	L42	1	41 and radial	USPA T	2004/10/08 15:57	
39	BRS	L43	1	42 and planar	USPA T	2004/10/08 15:57	
40	BRS	L44	146	4 and (arcuate)	USPA T	2004/10/08 16:08	
41	BRS	L45	0	44 and ((non-planar or non adj planar) near4 (prism))	USPA T	2004/10/08 16:05	
42	BRS	L46	0	44 and (pachan )	USPA T	2004/10/08 16:08	
43	BRS	L48	0	47 and belt	USPA T	2004/10/08 16:08	
44	BRS	L49	0	47 and pulley	USPA T	2004/10/08 16:08	
45	BRS	L47	5	44 and (dove near3 prism)	USPA T	2004/10/08 16:08	
46	IS&R	L50	43394	(382/124).CCLS. or ("356").CLAS.	USPA T	2004/10/08 16:07	
47	BRS	L51	882	50 and (arcuate)	USPA T	2004/10/08 16:20	
48	BRS	L53	1	52 and pulley	USPA T	2004/10/08 16:08	

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49	BRS	L54	1	53 and belt	USPA T	2004/10/0 8 16:08	
50	BRS	L55	0	54 and (pachan )	USPA T	2004/10/0 8 16:08	
51	BRS	L57	0	55 and rotat\$5	USPA T	2004/10/0 8 16:09	
52	BRS	L56	1	54 and optical	USPA T	2004/10/0 8 16:09	
53	BRS	L60	0	58 and scanner	USPA T	2004/10/0 8 16:10	
54	BRS	L58	1	56 and scan\$4	USPA T	2004/10/0 8 16:24	
55	BRS	L61	1	58 and rotat\$5	USPA T	2004/10/0 8 16:23	
56	BRS	L62	1	61 and path	USPA T	2004/10/0 8 16:11	
57	BRS	L63	1	62 and prism	USPA T	2004/10/0 8 16:11	
58	BRS	L64	1	63 and radial	USPA T	2004/10/0 8 16:12	
59	BRS	L65	0	64 and (CCD or camera or video or captur\$4)	USPA T	2004/10/0 8 16:12	
60	BRS	L66	1	64 and mov\$5	USPA T	2004/10/0 8 16:19	
61	BRS	L52	4	51 and (dove near3 prism)	USPA T	2004/10/0 8 16:23	
62	BRS	L67	26	radial and (arcuate near4 patch)	USPA T	2004/10/0 8 16:18	
63	BRS	L68	94	4 and ( radial near3 scan\$4)	USPA T	2004/10/0 8 16:22	
64	BRS	L69	4	68 and (arcuate)	USPA T	2004/10/0 8 16:22	
65	BRS	L70	398	1 and ( radial near3 scan\$4)	USPA T	2004/10/0 8 16:22	
66	BRS	L71	43	70 and (arcuate)	USPA T	2004/10/0 8 16:34	
67	BRS	L72	109	70 and prism	USPA T	2004/10/0 8 16:34	
68	BRS	L73	105	72 and rotat\$5	USPA T	2004/10/0 8 16:35	
69	BRS	L74	10	73 and (dove near3 prism)	USPA T	2004/10/0 8 16:24	
70	BRS	L75	10	74 and scan\$4	USPA T	2004/10/0 8 16:35	
71	BRS	L76	8	75 and scanner	USPA T	2004/10/0 8 16:35	
72	BRS	L77	0	76 and (arcuate)	USPA T	2004/10/0 8 16:34	
73	BRS	L78	5	71 and prism	USPA T	2004/10/0 8 16:35	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Comments
74	BRS	L79	5	78 and rotat\$5	USPA T	2004/10/0 8 16:35	
75	BRS	L81	2	80 and scanner	USPA T	2004/10/0 8 16:35	
76	BRS	L80	5	79 and scan\$4	USPA T	2004/10/0 8 16:36	

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**JNL** = Journal or Magazine   **CNF** = Conference   **STD** = Standard**1 Nonmechanical image rotation with an acousto-optic dove prism***Eung Gi Paek; Choe, J.Y.; Oh, T.K.; Hong, J.H.; Chang, T.Y.;*  
Lasers and Electro-Optics, 1998. CLEO 98. Technical Digest. Summaries of papers presented at the Conference on , 3-8 May 1998

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Pattern Recognition, 1994. Vol. 3 - Conference C: Signal Processing, Proceedings of the 12th IAPR International Conference on , October 9-13, 1994  
Pages:345 - 348 vol.3[\[Abstract\]](#) [\[PDF Full-Text \(388 KB\)\]](#) **IEEE CNF****3 High-isolation polarization-independent quasi-optical circulator***Fujii, Y.;*  
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**5 Continuously tuned external cavity semiconductor laser**

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**6 Polarization-independent tunable wavelength-selective filter using liquid crystal**

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**14 A dual-fiber optical rotary joint**

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